MANUFACTURER DOCUMENT PACKAGE

Manufacturer's Manual

Reference package for procurement and maintenance review

SCHNEIDER ELECTRIC

ATV930D30N4

VARIABLE SPEED DRIVE

Used with the applicable Altivar Process ATV900 configuration.

REFERENCE PACKAGE

OFFICIAL DOCUMENT

Selected official manufacturer pages follow this cover.

Source: Schneider Electric ATV930D30N4 technical data and applicable product instructions

Product data sheet
Characteristics

ATV930D30N4
Variable speed drive, Altivar Process ATV900, ATV930, 30 kW, 400/480 V, with braking unit, IP21



Main

Range of product	Altivar Process ATV900
Device application	Industrial application
Product or component type	Variable speed drive
Product destination	Asynchronous motors Synchronous motors
Product specific application	Process for industrial
Variant	With braking chopper Standard version
Network number of phases	3 phases
Mounting mode	Wall mount
Communication port protocol	Modbus serial EtherNet/IP Modbus TCP
[Us] rated supply voltage	380...480 V - 15...10 %
Motor power kW	30.0 KW for normal duty 22.0 KW for heavy duty
Motor power hp	40.0 Hp for normal duty 30.0 Hp for heavy duty
Continuous output current	61.5 A at 4 kHz for normal duty 46.3 A at 4 kHz for heavy duty
EMC filter	Integrated With EMC plate option
IP degree of protection	IP21
Degree of protection	UL type 1
Option card	Slot A: communication module for Profibus DP V1 Slot A: communication module for PROFINET Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module communication module for Ethernet Powerlink
Discrete input logic	16 preset speeds
Asynchronous motor control profile	Constant torque standard Variable torque standard Optimized torque mode

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Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	599 Hz
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Nominal switching frequency	4 kHz
Line current	53.3 A at 380 V (normal duty) 40.5 A at 380 V (heavy duty) 45.9 A at 480 V (normal duty) 35.8 A at 480 V (heavy duty)
Apparent power	38.1 KVA at 480 V (normal duty) 29.8 KVA at 480 V (heavy duty)
Maximum transient current	73.8 A during 60 s (normal duty) 69.5 A during 60 s (heavy duty)
Network frequency	50...60 Hz
Prospective line Isc	50 KA

Complementary

Discrete input number	10
Discrete input type	DI1...DI8 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 0…30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm
Discrete output number	2
Discrete output type	Logic output DQ+ 0…1 kHz <= 30 V DC 100 mA Programmable as pulse output DQ+ 0…30 kHz <= 30 V DC 20 mA Logic output DQ- 0…1 kHz <= 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles
Maximum switching current	Relay output R1 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Physical interface	Ethernet 2-wire RS 485
Connector type	2 RJ45 1 RJ45
Method of access	Slave Modbus TCP
Transmission rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s
Transmission frame	RTU
Number of addresses	1…247
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
4 quadrant operation possible	True

Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Motor slip compensation	Can be suppressed Automatic whatever the load Adjustable Not available in permanent magnet motor law
Braking to standstill	By DC injection
Brake chopper integrated	True
Maximum input current	53.3 A
Maximum output voltage	480.0 V
Relative symmetric network frequency tolerance	5 %
Base load current at high overload	46.3 A
Base load current at low overload	61.5 A
Power dissipation in W	Natural convection: 93 W at 380 V, switching frequency 4 kHz Forced convection: 640 W at 380 V, switching frequency 4 kHz
With safety function Safely Limited Speed (SLS)	True
With safety function Safe brake managemen-t (SBC/SBT)	True
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Quantity per set	1
Width	226 Mm
Height	673 Mm
Depth	274 Mm
Product weight	28 Kg
Electrical connection	Control: screw terminal 0.5...1.5 mm²/AWG 20...AWG 16 Line side: screw terminal 25...50 mm²/AWG 4...AWG 1 Motor: screw terminal 25...50 mm²/AWG 4...AWG 1 DC bus: screw terminal 25...50 mm²/AWG 4...AWG 1
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1…247 for Modbus serial
Supply	External supply for digital inputs: 24 V DC (19…30 V), <1.25 mA, protection-type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V D-C +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21…27 V), <200 mA, protec-tion type: overload and short-circuit protection

Local signalling	Local diagnostic: 3 LED (mono/dual colour) Embedded communication status: 5 LED (dual colour) Communication module status: 2 LED (dual colour) Presence of voltage: 1 LED (red)
Input compatibility	DI1...DI8: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Sampling duration	2 Ms +/- 0.5 ms (DI1...DI8) - discrete input 5 Ms +/- 1 ms (DI7, DI8) - pulse input 1 Ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 Ms +/- 1 ms (AQ1, AQ2) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Isolation	Between power and control terminals

Environment

Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	TÜV CSA UL
Marking	CE
Standards	UL 508C EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Maximum THDI	<48 % from 80...100 % of load conforming to IEC 61000-3-12
Assembly style	Enclosed
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
Maximum acceleration under shock impact (during-operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational-stress (during operation)	10 m/s² at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	240 M3/H
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	71.5 DB conforming to 86/188/EEC
Vibration resistance	1.5 mm peak to peak (f= 2…13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13…200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3
Relative humidity	5…95 % without condensation conforming to IEC 60068-2-3

Ambient air temperature for operation	-15…50 °C (without derating) 50…60 °C (with derating factor)
Noise level	71.5 DB
Pollution degree	2
Ambient air transport temperature	-40…70 °C
Ambient air temperature for storage	-40…70 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	50.0 Cm
Package 1 Width	34.5 Cm
Package 1 Length	84.5 Cm
Package 1 Weight	28.7 Kg

Offer Sustainability

Sustainable offer status	Green Premium product
REACh Regulation	REACh Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
China RoHS Regulation	China RoHS Declaration
RoHS exemption information	Yes
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End Of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov
Upgradeability	Upgraded components available

Product Life Status : Commercialised